



SMART
MARITIME



WIND PROPULSION ANALYSIS

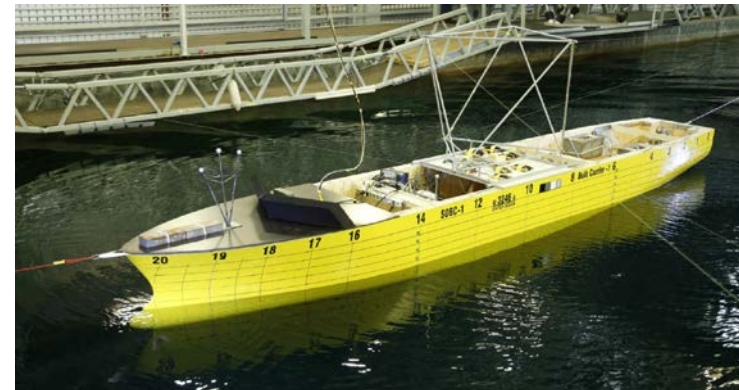
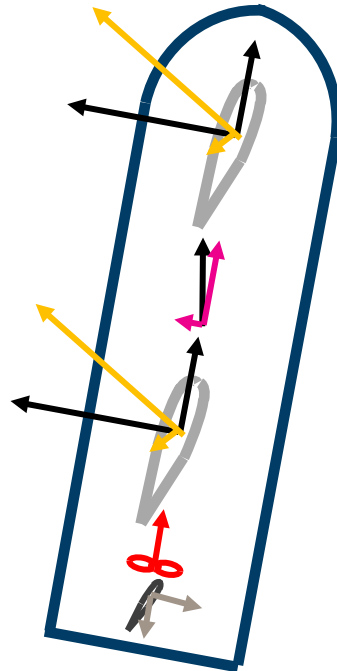
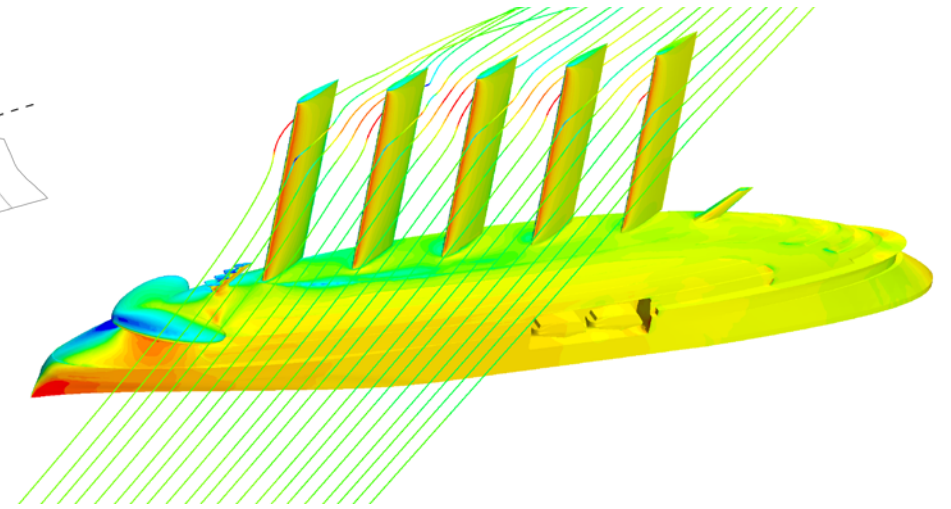
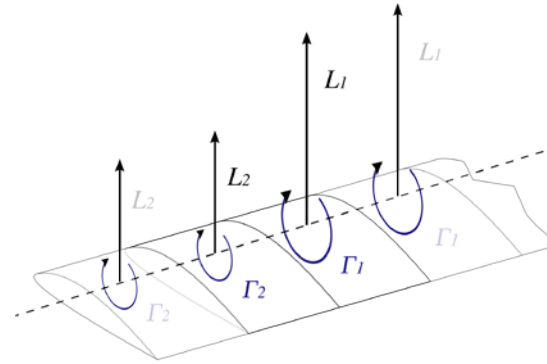
Anders Östman, SINTEF Ocean
June 20, 2023 - Trondheim

sf = Centre for
Research-based
Innovation

The Research Council of Norway

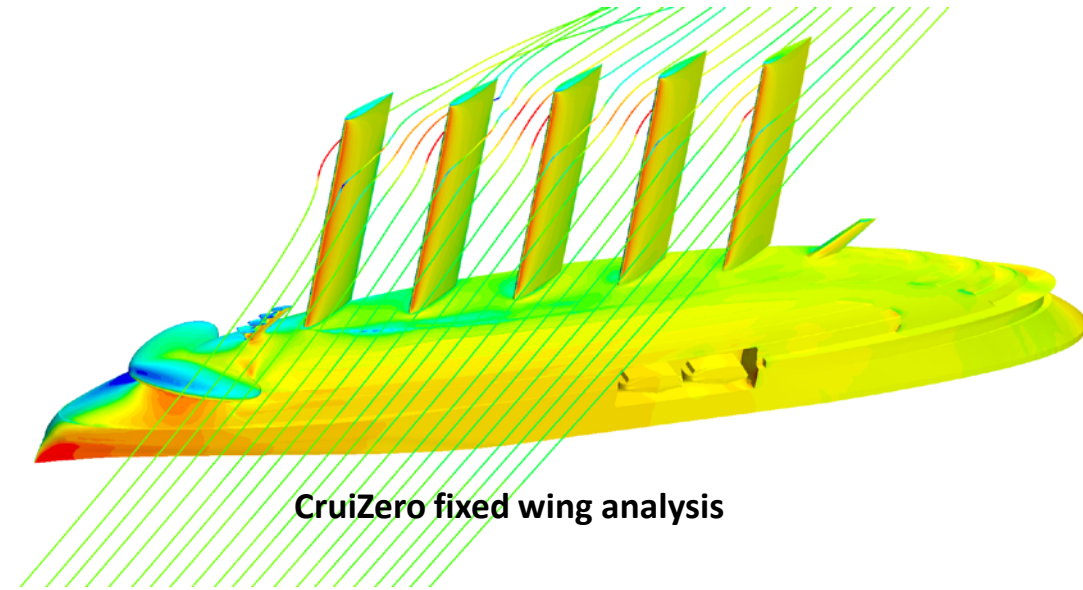
Numerical and model test methods for WASP assessment

- CFD
- Lifting Line
- SteadySail
- Hybrid model test



CFD

- CFD can be used to analyze interactions between multiple sails including the influence of the superstructure
- Combines the effect of ship velocity and atmospheric boundary layer profile
- Resource demanding, calculation time in the order of ~hour(s)



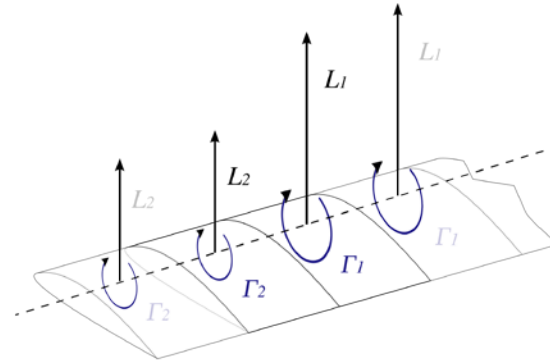
Benefits using CFD:

- Analyze and understand complex flow features
- Calculate 2D profile lift and drag data (input to lifting line solver)
- Can be used to validate/verify lifting line solver results

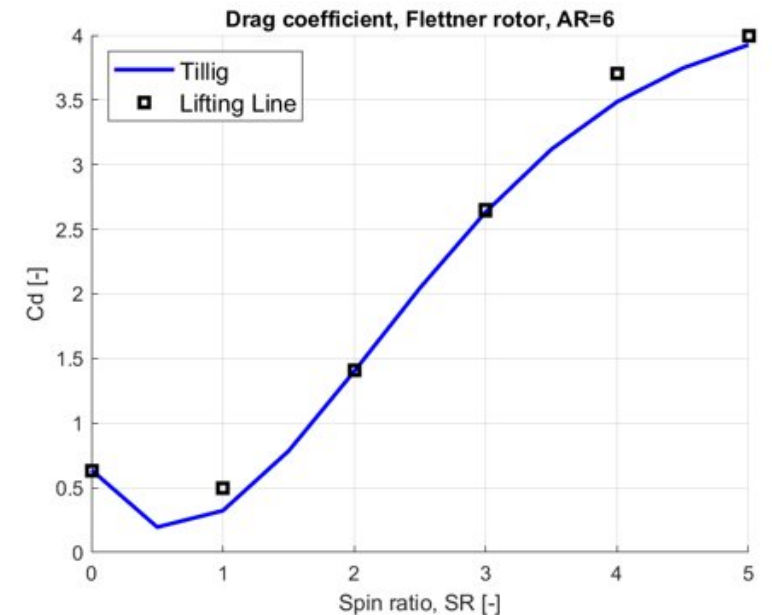
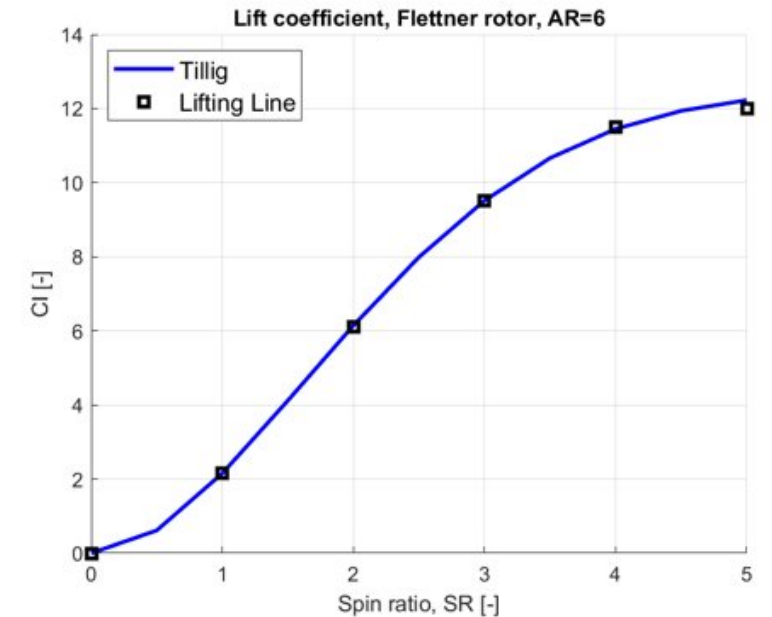
Limitations:

- Too demanding to be used in combination with performance analysis tools (SteadySail)
- Can only be used for a limited set of flow conditions
- Not suitable in early design studies

Lifting Line

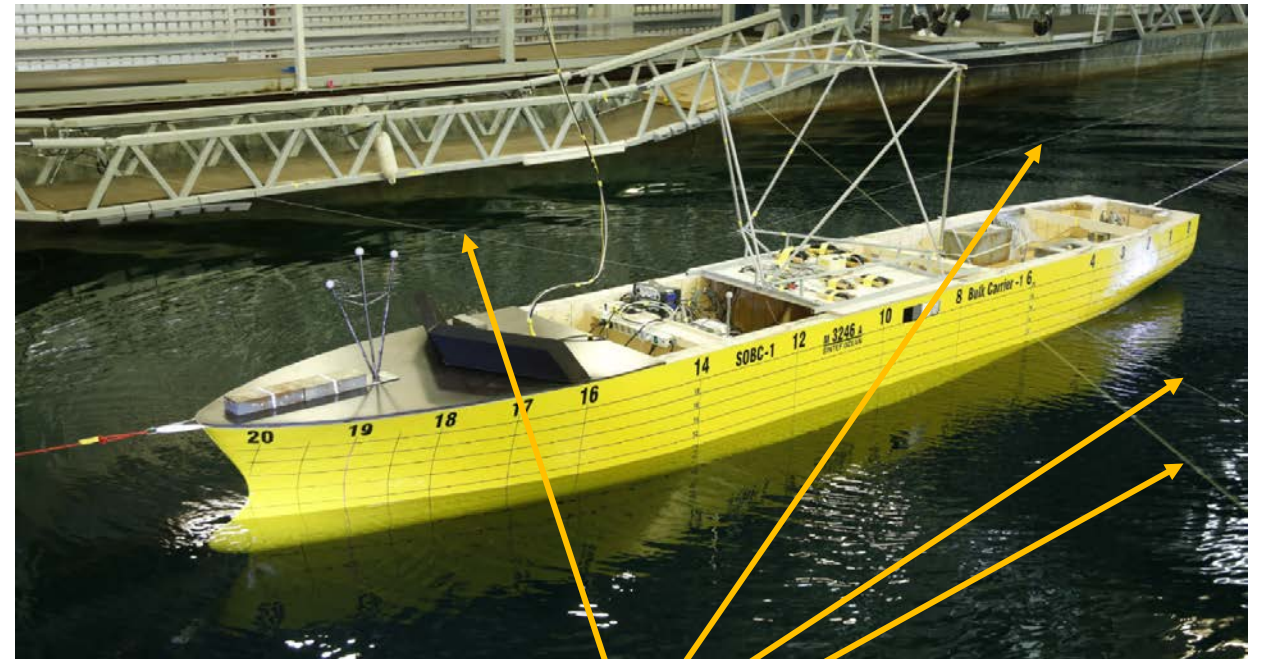


- Based on classic aerodynamic theory (Prandtl 1918)
- Use 2D profile lift and drag data as input
- Can calculate interaction between multiple sails
- **Fixed wing** and **Flettner rotor** models implemented
- Very fast (~10 ms)



Hybrid model tests

- Free running, self-propulsion
- Calculated forces added by wires to the model
- Course control with autopilot connected to rudder
- Investigate various conditions:
 - Constant wind speed and direction
 - Turbulent wind (including gusts)
 - In waves
 - Manoeuvring zig-zags



wires



20

19

18

17

16

14

SUBC-1

12

11

20

19

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17

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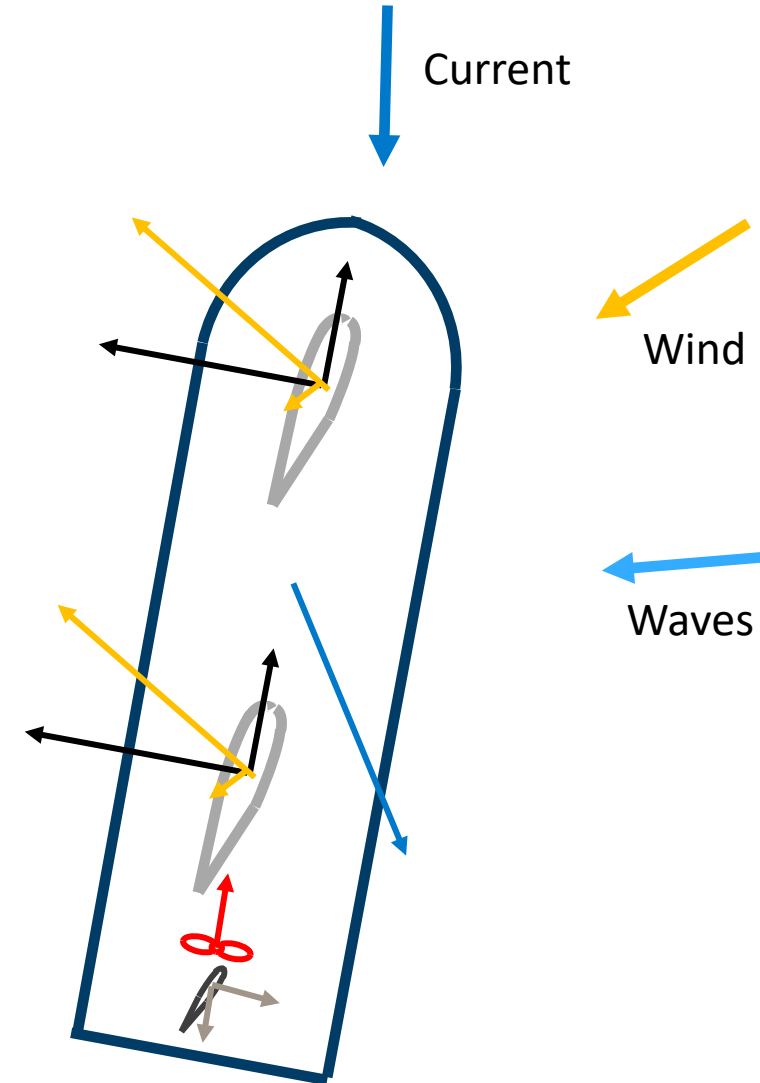
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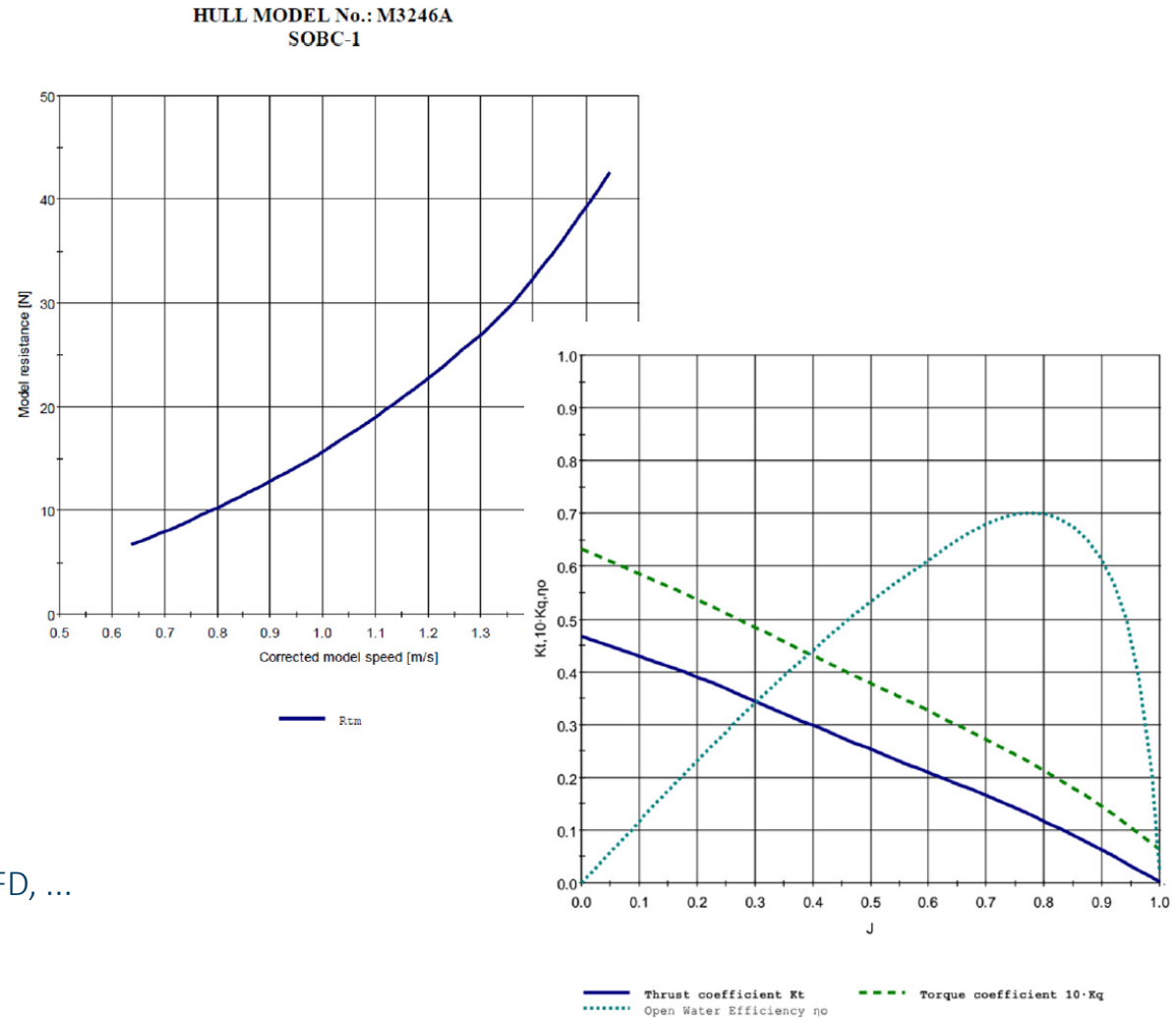
SteadySail Performance Prediction Program

- Simulation of a vessel sailing on a steady course
- 3 DOF: surge, sway, yaw
- Considers effects from:
 - Wind
 - Waves
 - Ocean current
 - Vessel velocity and attitude
 - Propellers and rudders
 - Wind propulsion devices
- Calculation modes:
 - Propulsion point for given speed
 - Speed for given propulsion point
- Standalone tool for power predictions
- Integrated in ShipX and Gymir route simulator



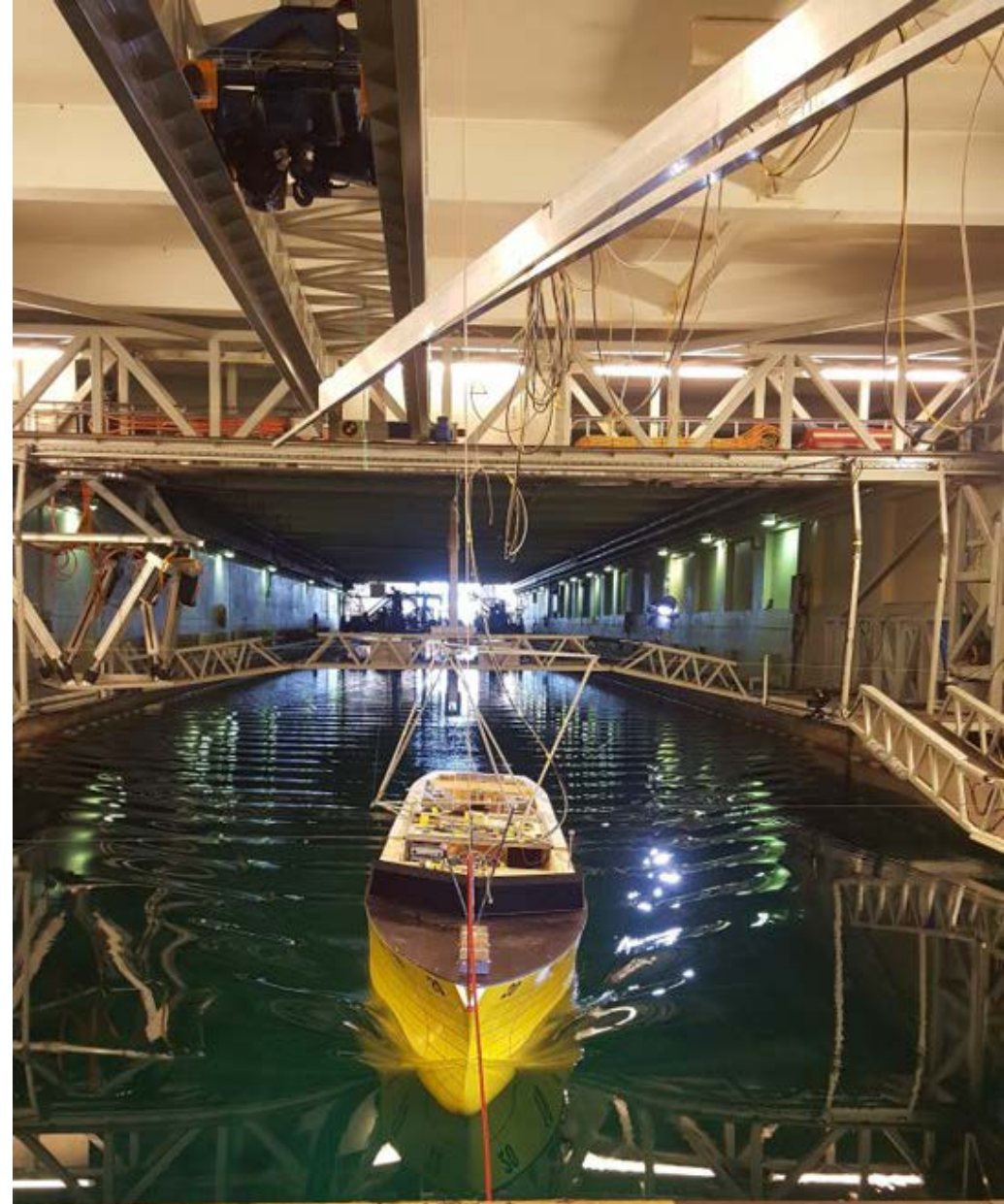
SteadySail input

- Manoeuvring model input
 - HullVisc (strip theory)
 - Model tests or CFD
- Propulsion input
 - Type
 - Geometry
 - Open water curves
 - Propulsive coefficients
- Wave drift coefficients
 - VERES, MULDIS, WAMIT, model tests, etc
- Superstructure aerodynamic coefficients
 - Blendermann library, custom input from wind tunnel, CFD, ...

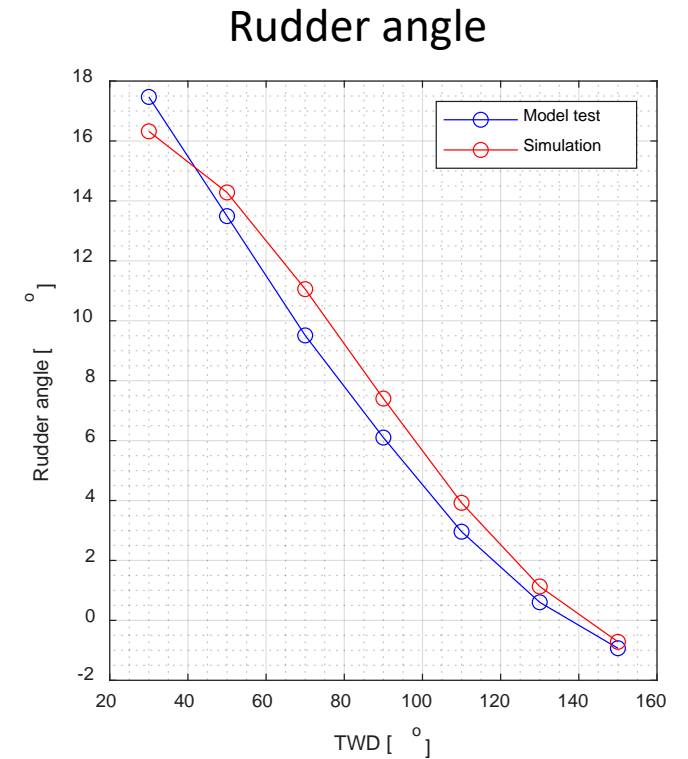
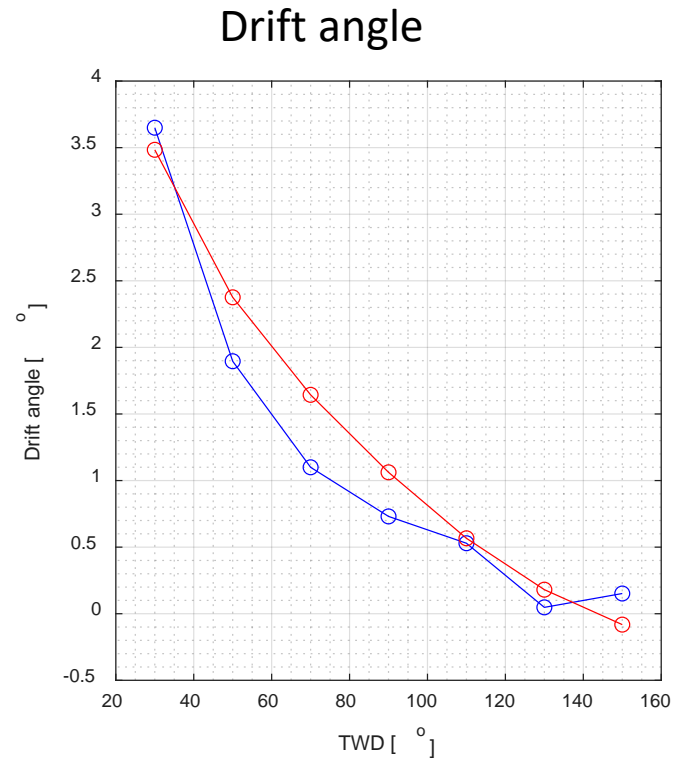
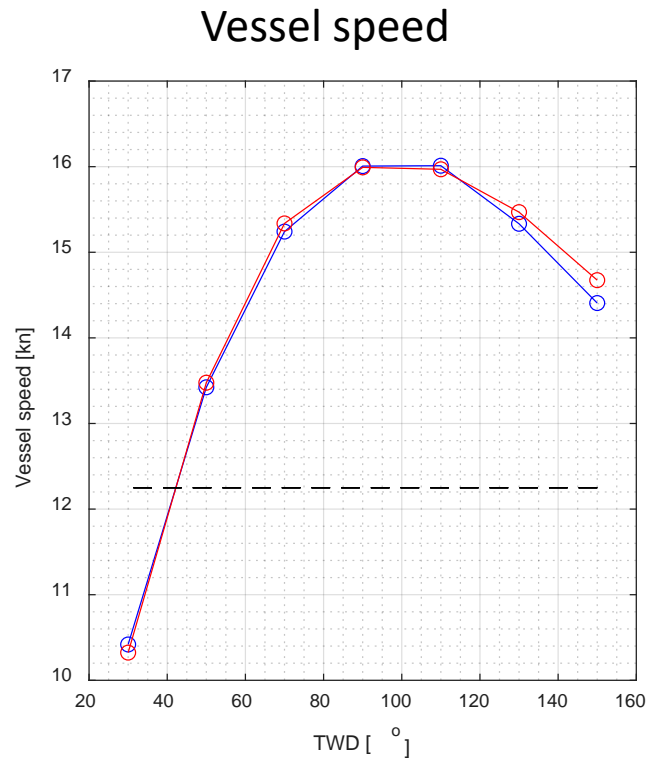


StedySail validation

- Hybrid model test cases for validation
 - SOBC (SINTEF Ocean Bulk Carrier)
 - Constant wind speed and direction
 - True wind speed: 10, 15 and 20 m/s
 - True wind direction: 30, 50, 70, 90, 110, 130, 150 degrees
 - Constant propeller power: 3078 kW
 - Constant Flettner rotor RPM: 180 RPM
 - No waves
 - No wind loads on hull

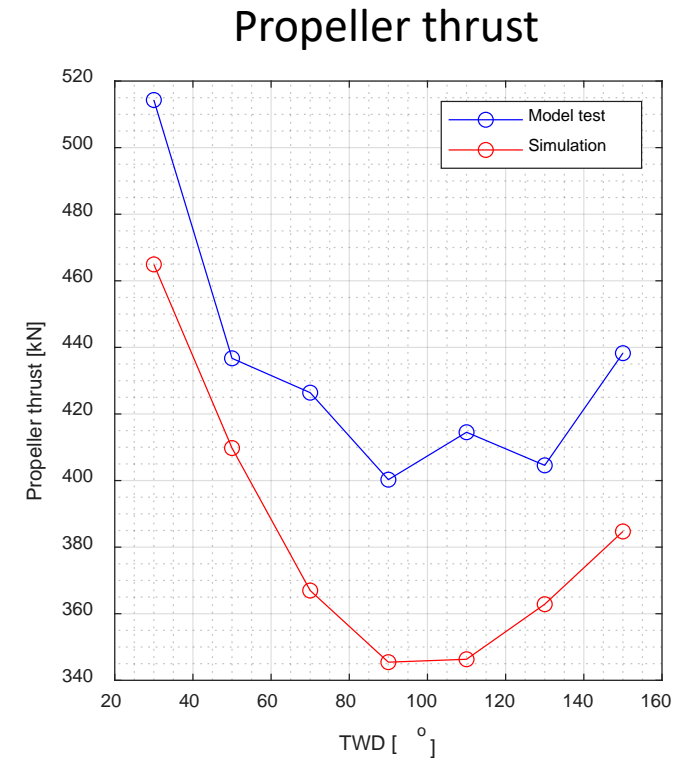
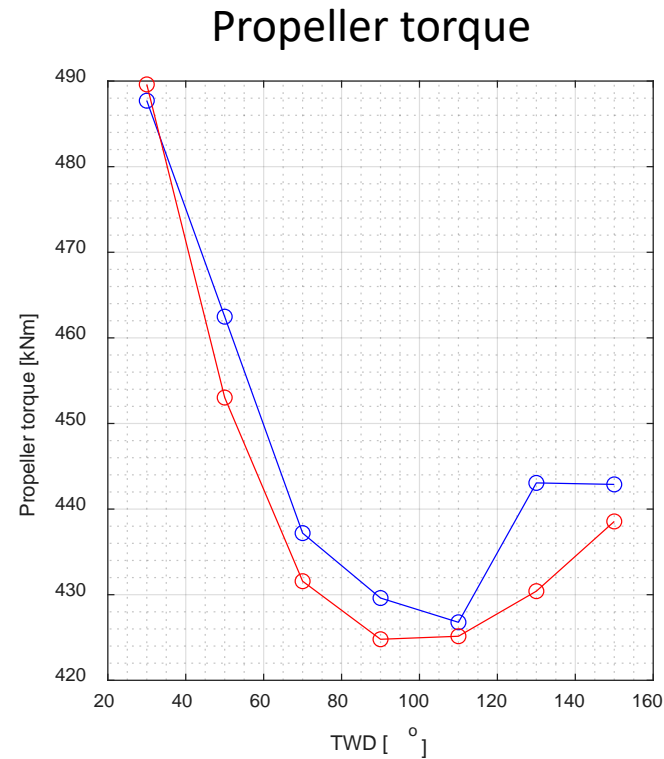
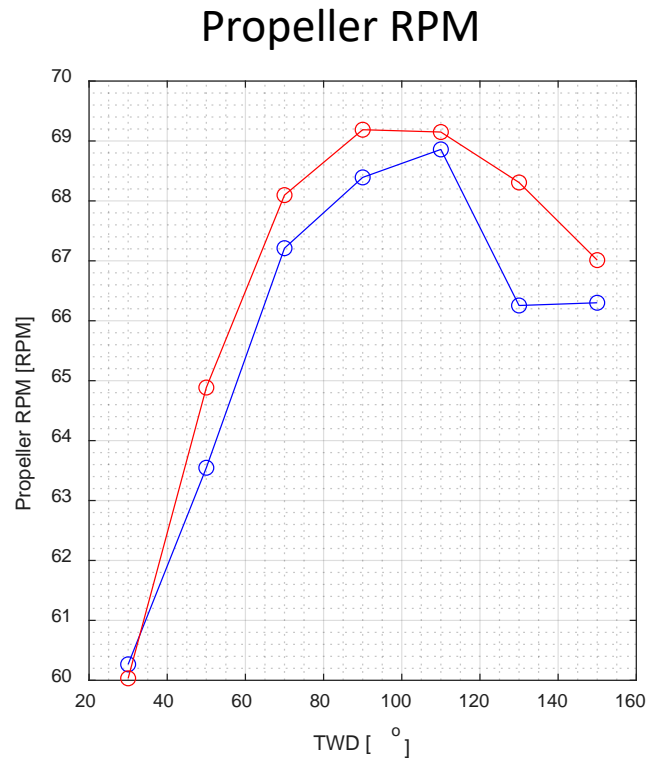


StedySail validation results



Simulated at 15m/s wind speed

StedySail validation results



Simulated at 15m/s wind speed

Summary and conclusions

- We are able to analyze wind propelled vessels both numerically and in model tests
 - BUT: Only at steady state in the simulations
- A fast Lifting Line aerodynamic solver has been implemented
 - Needs further developments for unsteady simulations
 - Models for **fixed wing** and **Flettner rotor**
 - Should be easy to implement a **suction wing** model
- Able to perform accurate model tests using hybrid testing methods

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